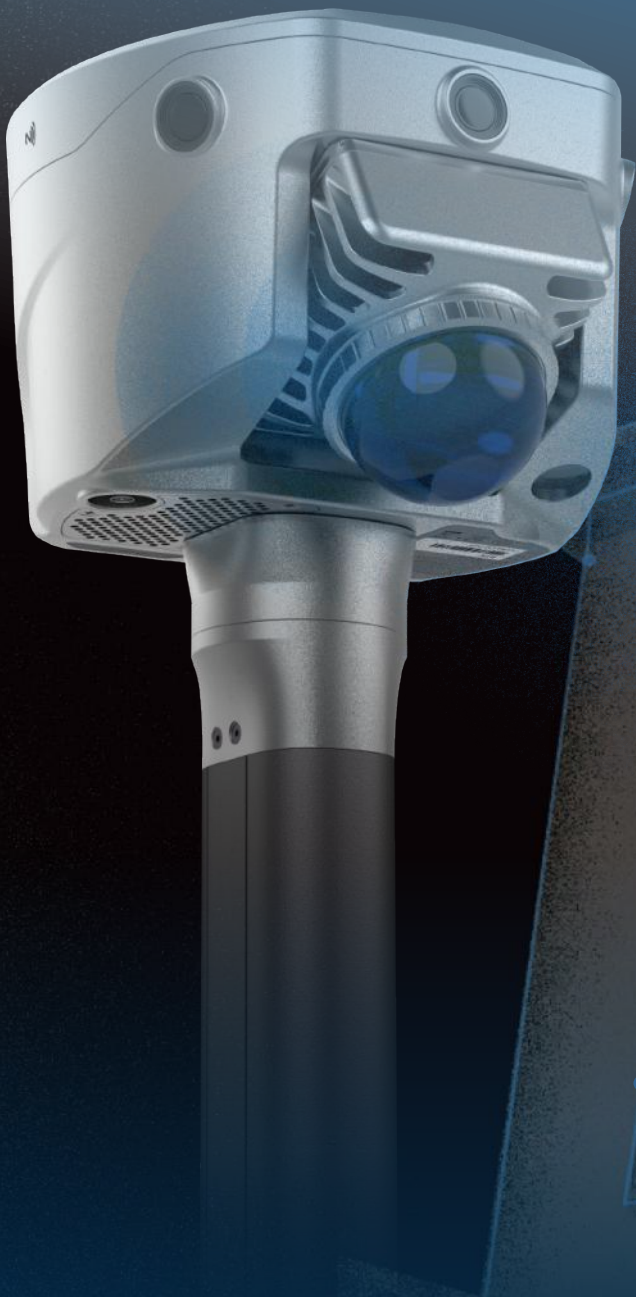


V700S

SLAM RTK





Full-Constellation Tracking: Strong Signal & High-Quality Data

- **Supports 1408 channels**
- **New GNSS SoC chip:** Low power consumption, extended battery life.
- **Advanced technology:** Advanced multi-frequency anti-interference and adaptive filtering technology ensures strong signal reception, high-quality data and excellent accuracy.



Innovative Industrial Design

- **Compact & lightweight** for easy handling.
- **Screw-lock mechanism** securely connects the device and battery handle, ensuring reliable and stable operation.

N:2542629.911

E:435687.323

H:2.645



Contactless Measurement

- Utilizing laser point cloud data and image data provides real-time acquisition of rich geospatial information efficiently and conveniently.
- This technology greatly expands the application scope of GNSS, allowing measurements in areas like under bridges, culverts, and enclosed spaces, ensuring efficient and safe operations.
- Leveraging Android's high-performance laser point cloud and image processing technology, users can simply take a photo to obtain coordinates of multiple points on the handheld software. With an accuracy of 5cm, it doubles working efficiency.



Unified Coordinate Framework

- RTK + SLAM Fusion: V700S delivers real-time centimeter-level positioning outdoors while automatically aligning point cloud data, ensuring unified coordinate output (BLH/NEH).
- Control-free scanning: V700S requires no control points, allowing users to scan freely without returning to previous locations - dramatically improving on-site efficiency.



Laser Reverse Positioning Technology: Precision Measurement without Signal

Hi-Target's innovative Laser Reverse Positioning Technology enables seamless cross-environment measurement. Outdoors, the high-precision RTK module delivers centimeter-level accuracy. In GNSS-denied areas like under bridges or eaves, the system automatically switches to laser-based positioning, ensuring uninterrupted data capture.





Real-time Volume Calculation

Through laser point cloud data, rich three-dimensional data of ground objects can be obtained in real time. By leveraging high-performance Android-based processing technology, quantitative results can be derived efficiently and conveniently.



8-INCH ROBUST TABLET



2.0GHz, 8 cores high-speed processor



6+128GB large memory



8200 mAh high capacity battery



Based on Android 10, more smooth operation



APPLICATIONS



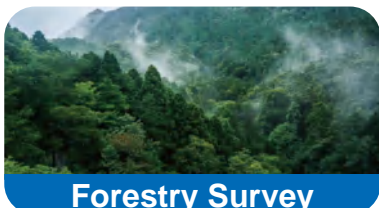
Urban Renewal



Volume Measurement



Tunnel Surveying



Forestry Survey



Underground Pipelines

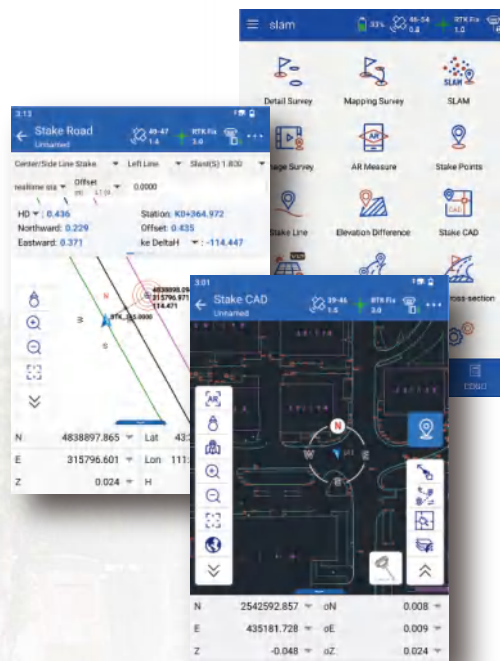


Architectural Survey

SOFTWARE

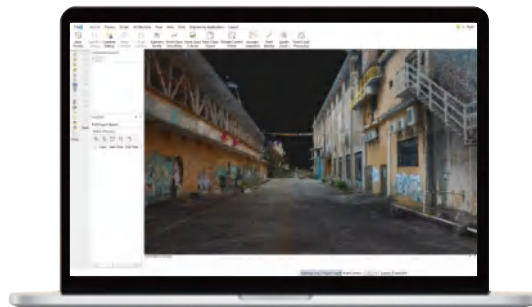
Hi-Survey Field Software

- High-performance laser point cloud & image processing engine for real-time solutions and visualization.
- Precision heat map display allows users to monitor accuracy in real time.
- Integrates industry-leading CAD & real-scene engines for an intuitive, visual measurement and layout experience.



Office Software for Post-processing

- Hi-LiDAR software refines real-time data, delivering point clouds with sub-2 cm thickness and <1 cm relative measurement precision.
- Automated excavation analysis: Calculates over/under-excavation for tunnel sections, enabling construction progress tracking and validation.
- Advanced section visualization & drafting: Supports horizontal/vertical section views, aiding in renovation planning for older buildings with precise architectural measurements.



AUTHORIZED DISTRIBUTION PARTNER

25A212

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TECHNICAL SPECIFICATIONS

| | | | |
|---|--|---|---|
| GNSS Configuration | Channel | 1408 | |
| | GNSS Signal | GPS: L1C/A, L1C, L2P(Y), L2C, L5 | |
| | | BDS: B1I, B2I, B3I, B1C, B2a, B2b | |
| | | GLONASS: L1, L2, L3 | |
| | | GALILEO: E1, E5a, E5b, E6 | |
| | | QZSS: L1, L2, L5, L6 | |
| | | NavIC: L5 | |
| | | SBAS: L1, L2, L5 | |
| | | PPP: B2b-PPP, E6-HAS | |
| | Output Format | ASCII: NMEA-0183, Binary | |
| System Configuration | Output Rate | 1Hz~20Hz | |
| | Static Data Format | GNS, Rinex | |
| | Real Time Kinematic | RTCM2.X, RTCM3.X | |
| Accuracy and Reliability ^[1] | Network Mode | VRS, FKP, MAC, Support NTRIP protocol | |
| | Operation System | Linux | |
| | Storage | Circulating 512GB ROM | |
| Camera | High-precision Static | H: 2.5 mm + 0.1 ppm RMS | V: 3.5 mm + 0.4 ppm RMS |
| | Static And Fast Static | H: 2.5 mm + 0.5ppm RMS | V: 5 mm + 0.5ppm RMS |
| | PPK | H: 8mm + 1ppm RMS | V: 15mm + 1ppm RMS |
| | PPP | H: 10cm | V: 20cm |
| | Code Differential Gnss Positioning | H: ±0.25m+1ppm RMS SBAS: 0.5m (H), 0.85m (V) | V: ±0.5m+1ppm RMS |
| | Real Time Kinematic (RTK) | H: 8mm+1ppm RMS Initialization time: Typically <10s | V: 15mm+1ppm RMS Initialization reliability: Typically > 99.9% |
| | Tilt Survey Performance ^[2] | 8mm+0.3mm/°tilt | |
| | Ar Stakeout | Support | |
| | Image Measurement | A single photo can acquire multiple point coordinates with an accuracy of 5cm ^[3] | |
| | Real-time Accuracy Evaluation | Supports | |
| Laser Scanner | Pixel | 3 professional HD cameras, 1bottom camera | |
| | Function | Support AR stakeout, image measurement, working distance 2~15m | |
| IMU | Range | 0.1~ 40m@10%, 0.1~ 70m@80% | |
| | Point Measurement Rate | 200,000 pts/sec | |
| | Laser Product Classification | Class 1 eye safe | |
| Communication | FOV | H: 160° | V: 59° |
| | Update Rate | 200Hz | |
| | I/O Interface | USB type C port; SMA antenna port; Nano SIM card slot | |
| | Network | TDD-LTE, FDD-LTE, GSM | |
| | Wi-Fi | IEEE 802.11a/b/g/n/ac/ax, 2.4GHz/5GHz, Wi-Fi hotspot | |
| Sensor | Bluetooth | Bluetooth 5.2 | |
| | Internal UHF Radio | Power: 0.5W/1W adjustable Frequence: 410MHz~470MHz | |
| | | Protocol: HI-TARGET, TRIMTALK450S, TRIMMARK III, SATEL-3AS, TRANSEOT, etc. | |
| Control Panel | Channel: 116 (16 scalable) | | |
| | Electronic Bubble | Supports | |
| | Tilt Survey | Built-in high-precision IMU module | |
| Application | Physical Button | Single button | |
| | Display | 2.8 inch, 480×640 pixel touchable screen | |
| | Led Lights | Mode, accuracy, network | |
| Physical | Advanced Function | NFC, WebUI, firmware upgrade via u-disk | |
| | Intelligence Application | Intelligent voice, self-check | |
| | Remote Service | Message push, online upgrade, remote control | |
| Environments | Power ^[4] | Lithium battery, portable charger RTK rover(UHF/Cellular): up to 10 hours SLAM mode: up to 5 hours USB 45W fast charging, fully charged in 2 hours | |
| | Size | Φ134.4mm×109.9mm | |
| | Weight | 1.68kg | |
| Environments | IP Rating | IP64 | |
| | Humidity | 100% non-condensing | |
| | Operation Temperature | -20 C ~+55 C | |
| | Storage Temperature | -40 C ~+70 C | |

Note:
^[1]The measurement accuracy, precision, reliability and initialization time depend on various factors, including tilt angle, number of satellites, geometric distribution, observation time, atmospheric conditions and multi-path validation, etc. The data are derived under normal conditions.
^[2]Irregular operations such as rapid rotation and high-intensity vibration may affect the inertial navigation accuracy.
^[3]The results are the accuracy obtained in laboratory scenarios, and some scenarios may have accuracy deviations.
^[4]The battery operating time is related to the operating environment, operating temperature and battery life.
 Descriptions and Specifications are subject to change without notice.